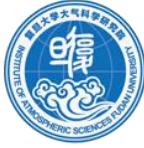




復旦大學
大气与海洋科学系
DEPARTMENT OF ATMOSPHERIC AND OCEANIC SCIENCES
FUDAN UNIVERSITY



復旦大學
大气科学研究院
INSTITUTE OF ATMOSPHERIC SCIENCES
FUDAN UNIVERSITY

新的分析误差估计方法及其在中国气象局 业务全球同化预报系统中的应用

冯杰

fengjieff@fudan.edu.cn

大气与海洋科学系/大气科学研究院，复旦大学

王金成

中国气象局地球系统数值预报中心

致谢：戴国锟，周非凡，段晚锁，刘永柱，张林，穆穆，雷荔儒等

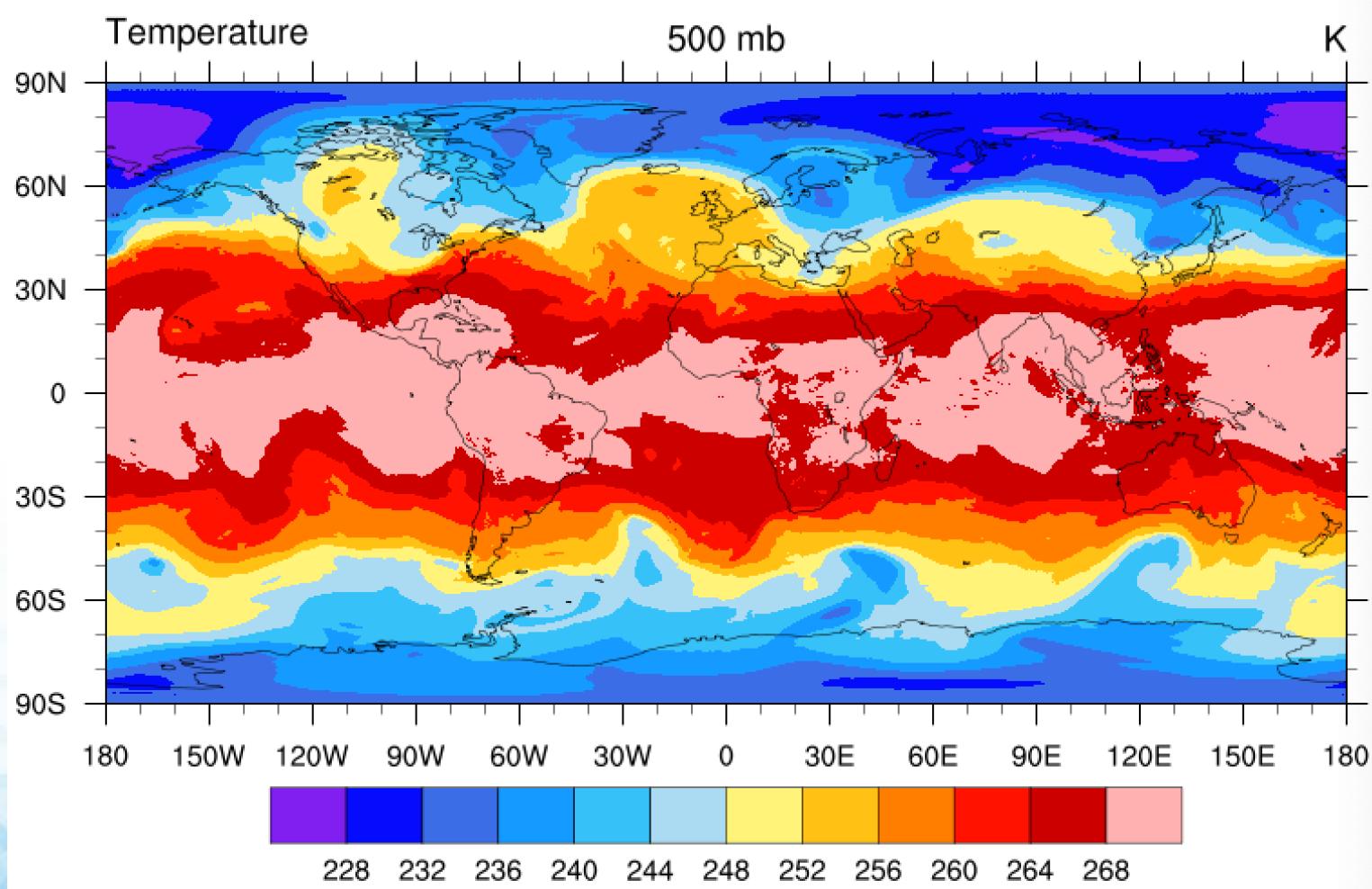
第五届全国中尺度气象学论坛，2023-8-11，银川

Outline

- **Background and motivation**
- **Methodology and validation**
- **Results of the operational GRAPES_GFS model at CMA**
- **Conclusions and discussion**

Background

A randomly selected analysis field



Analysis error (Analysis - Truth), how to measure?

Background

Accurate estimates of error variances in numerical analyses and forecasts are critical:

- Evaluation of Data Assimilation (DA) and forecast system
- Tuning of DA system
- Proper initialization of ensemble forecasts
- Understanding uncertainties in Climate reanalysis

Traditional methods:

- Observations as proxy
 - Sparse observations – no gridded information
 - Fraught with observational error (including representativeness error)
- DA schemes themselves
 - Computationally expensive
 - Affected by same assumptions used in DA scheme, potentially biased/inaccurate estimates
- Analysis in other DA systems as proxy
 - Independent?
 - Errors in analysis

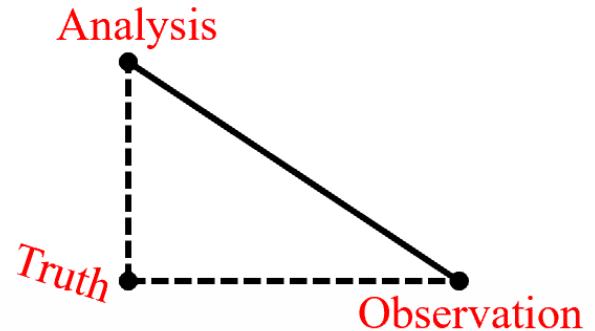
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- Evaluation of Data Assimilation (DA) and forecast system
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传统方法大多是经验性的，存在理论上的不合理性和偏差

Traditional methods

➤ Observations as proxy

- Sparse observations – no gridded information
- Fraught with observational error (including representativeness error)

➤ DA schemes themselves

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➤ Analysis in other DA systems as proxy

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Analysis

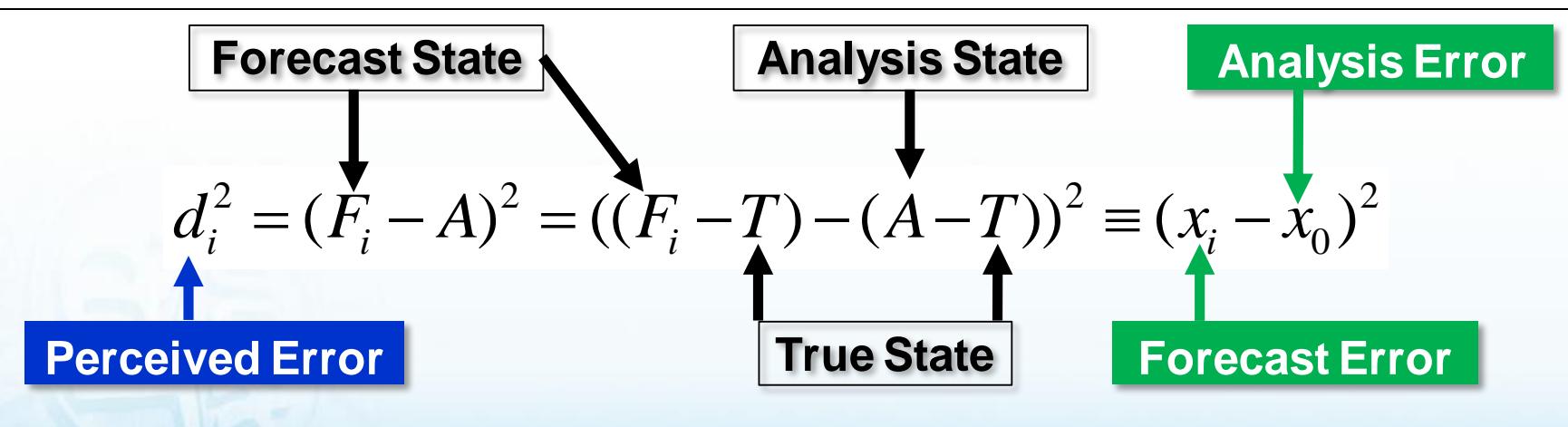
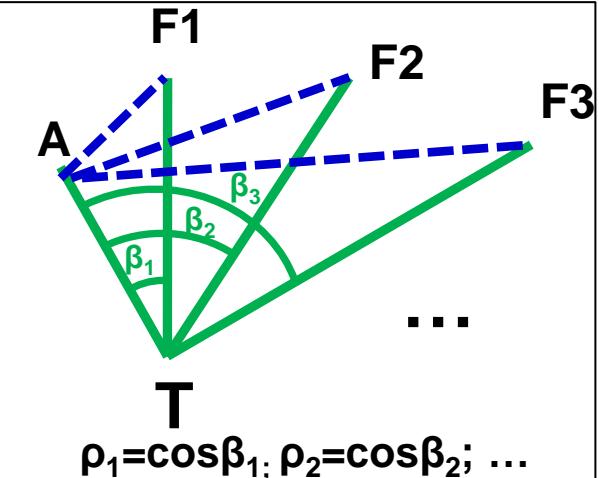
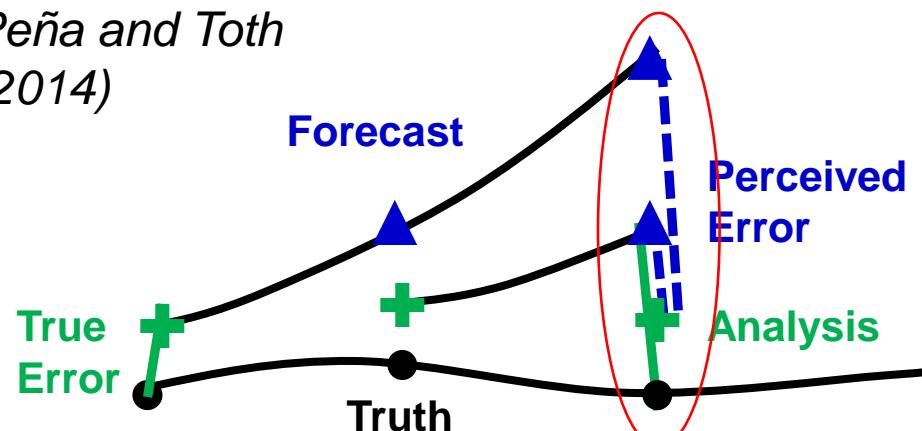
Truth

Observation



Statistical Analysis and Forecast Error (SAFE) Estimation

Peña and Toth
(2014)



Measurements

$$d_i^2 = x_0^2 + x_i^2 - 2\rho_i x_0 x_i$$

Estimated quantities

Can we estimate unknown parameters with observed quantities?

Cost Function and Relevant Assumptions

$$\underline{d_i^2} = \overline{x_0^2 + x_i^2 - 2\rho_i x_0 x_i}$$

Measurements **Estimated quantities**

Cost Function

$$J = \max(|d_i^2 - \hat{d}_i^2|) \cdot w_i^{-1}$$

- max : L_∞norm
- Sampling standard error of the mean (SEM)
- Minimization: Limited-memory BFGS

$$SEM_i = \frac{sd_i}{\sqrt{N}} \cdot f$$

$$f = \sqrt{(1+r_1)(1-r_1)}$$

$$w_i = \frac{SEM_i}{\sum_i SEM_i}$$

Peña and
Toth
(2014)

Connect measurements to estimates:

1. How true error grows in time;
2. How true forecast errors get decorrelated from true analysis errors with increasing lead time.

$$\rho_i = \rho_1^i$$

Exponential

$$x_i^2 = x_0^2 e^{\alpha t_i}$$

Logistic

$$x_i^2 = \frac{S_\infty \cdot c}{e^{-\alpha t_i} + c}$$

$$c = x_0^2 / (S_\infty - x_0^2)$$

α : **Growth Rate** S_∞ : **Saturation Value**

Validate Assumption 1 using GFS OSSE data

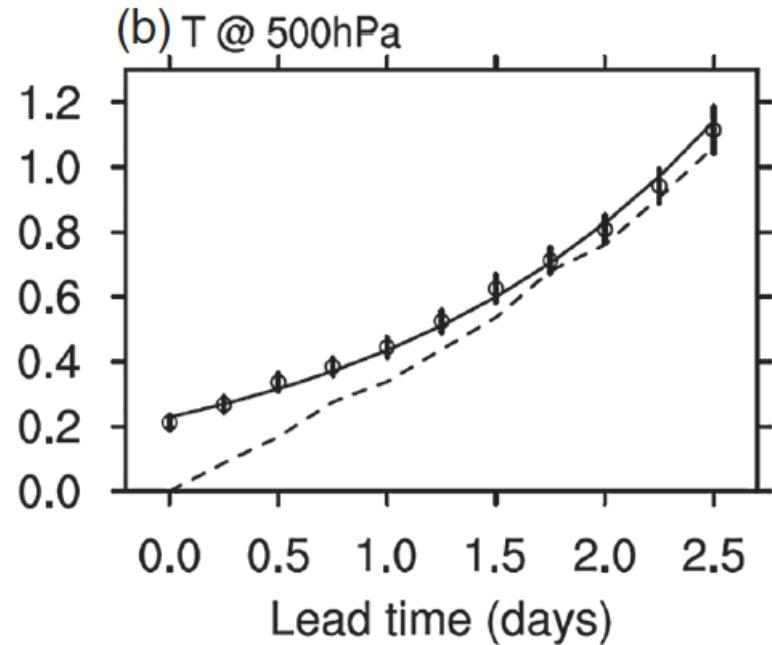
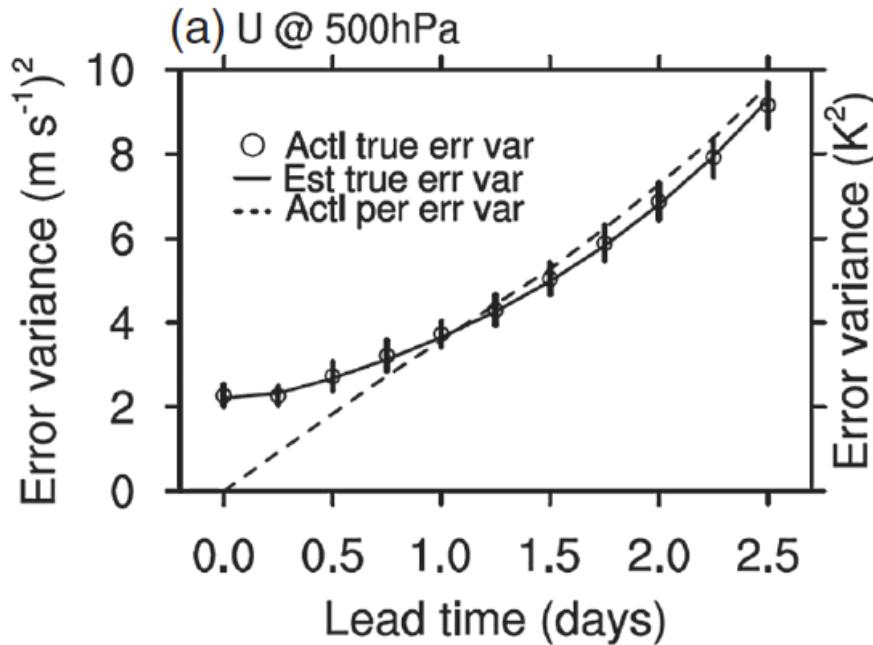
Truth is known

Ground truth: ECMWF operational model version c31r1

Analysis & Forecast model: NCEP GFS model

Data assimilation: 3DVar

Time period of samples: 3 July to 26 August 2005, 24-hour interval

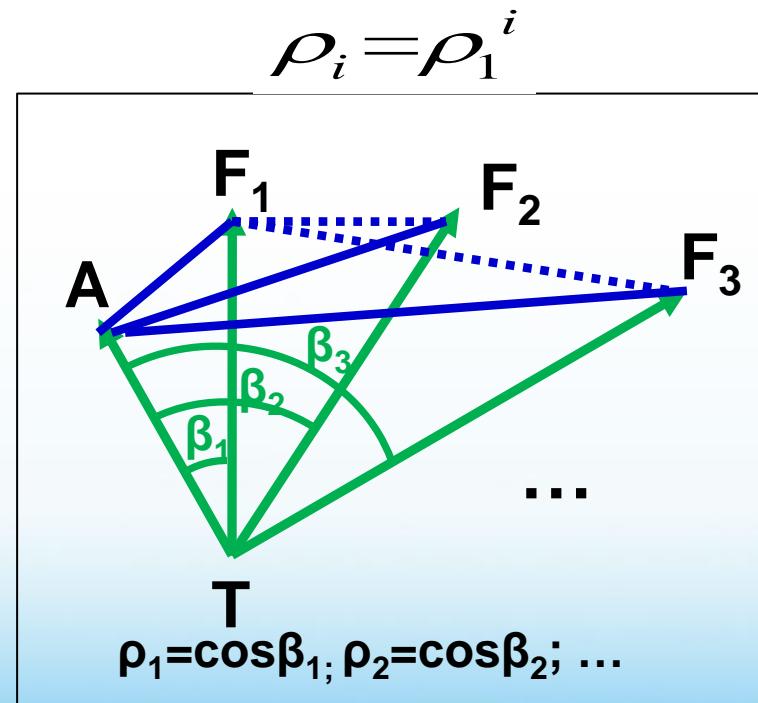


Short-range true forecast error variance almost grows exponentially!

Feng et al. (2020, QJRMS)

Analysis / Forecast Error Correlation

- With no DA step, analysis & forecast errors correlate at 1.0
- With one DA step, errors become de-correlated, $1 > \rho_1 > 0$;
- The effectiveness of forecast errors in sampling analysis errors decays exponentially in time



Validate Assumption 2 using GFS OSSE data

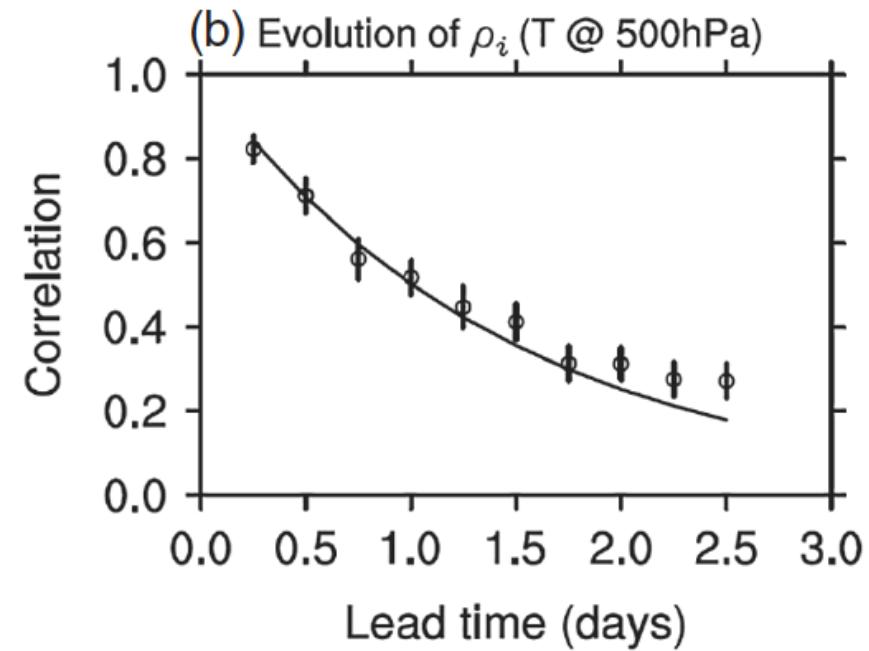
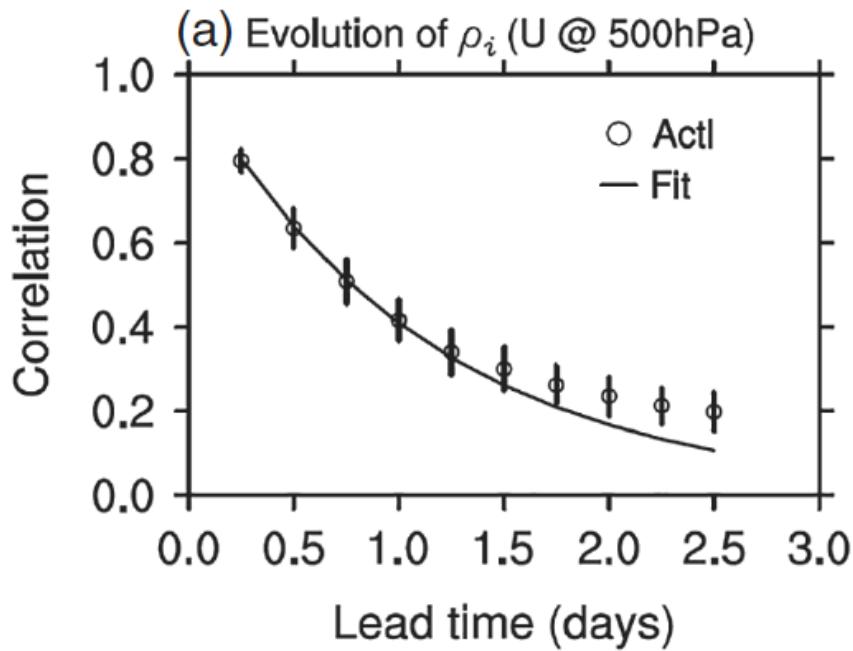
Truth is known

Ground truth: ECMWF operational model version c31r1

Analysis & Forecast model: NCEP GFS model

Data assimilation: 3DVar

Time period of samples: 3 July to 26 August 2005, 24-hour interval



$$\rho_i = \rho_1^i$$

SAFE方法的发展 (*Feng et al. 2017, Tellus; 2020, 2023 QJRMS*)

- SAFE方法的cost function是多元高阶非线性函数，最小化求解极易受采样误差的影响而不稳定，无法估计格点分析误差
- Feng et al. (2017) 在cost function中引入了额外的限制项
 - ✓ 利用滞后预报偏差的指数误差增长对真实误差增长参数(α)进行限制（假定模式误差很小），极大减小采样误差的影响

$$\begin{aligned} J = & \max \left(\left| f_i^{2'} - f_i^2 \right| \cdot w_i \right) (i = 0, 1, \dots, n) \\ & + \max \left(\left| f_{i,j}^{2'} - f_{i,j}^2 \right| \cdot w_{i,j} \right) (i = 0, 1, \dots, m), \end{aligned}$$

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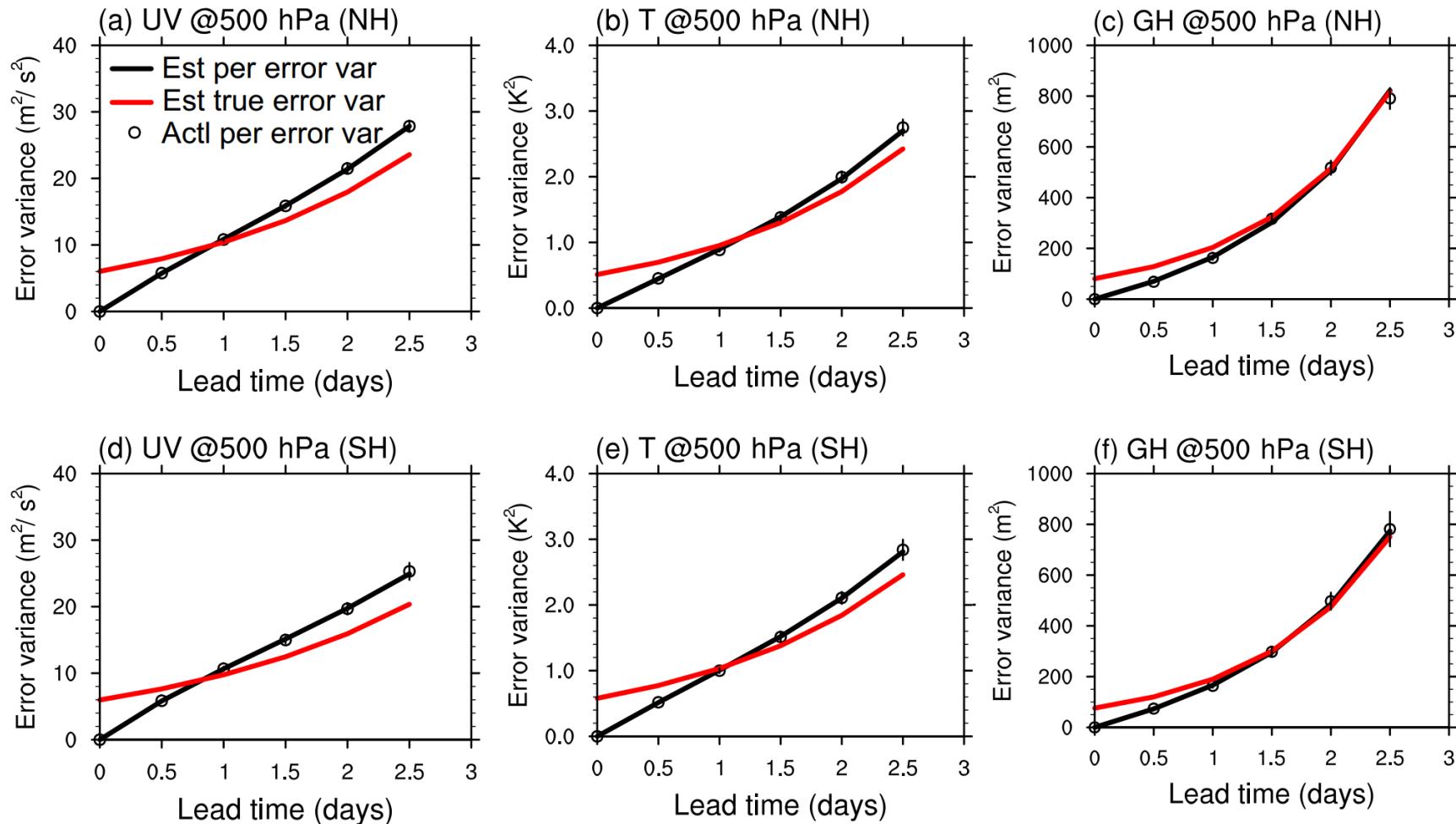
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$$+ \boxed{\max \left(\left| f_{i,j}^{2'} - f_{i,j}^2 \right| \cdot w_{i,j} \right) (i = 0, 1, \dots, m)},$$

Short-range Evolution of Forecast Error Variance @Dec2021-Feb2022

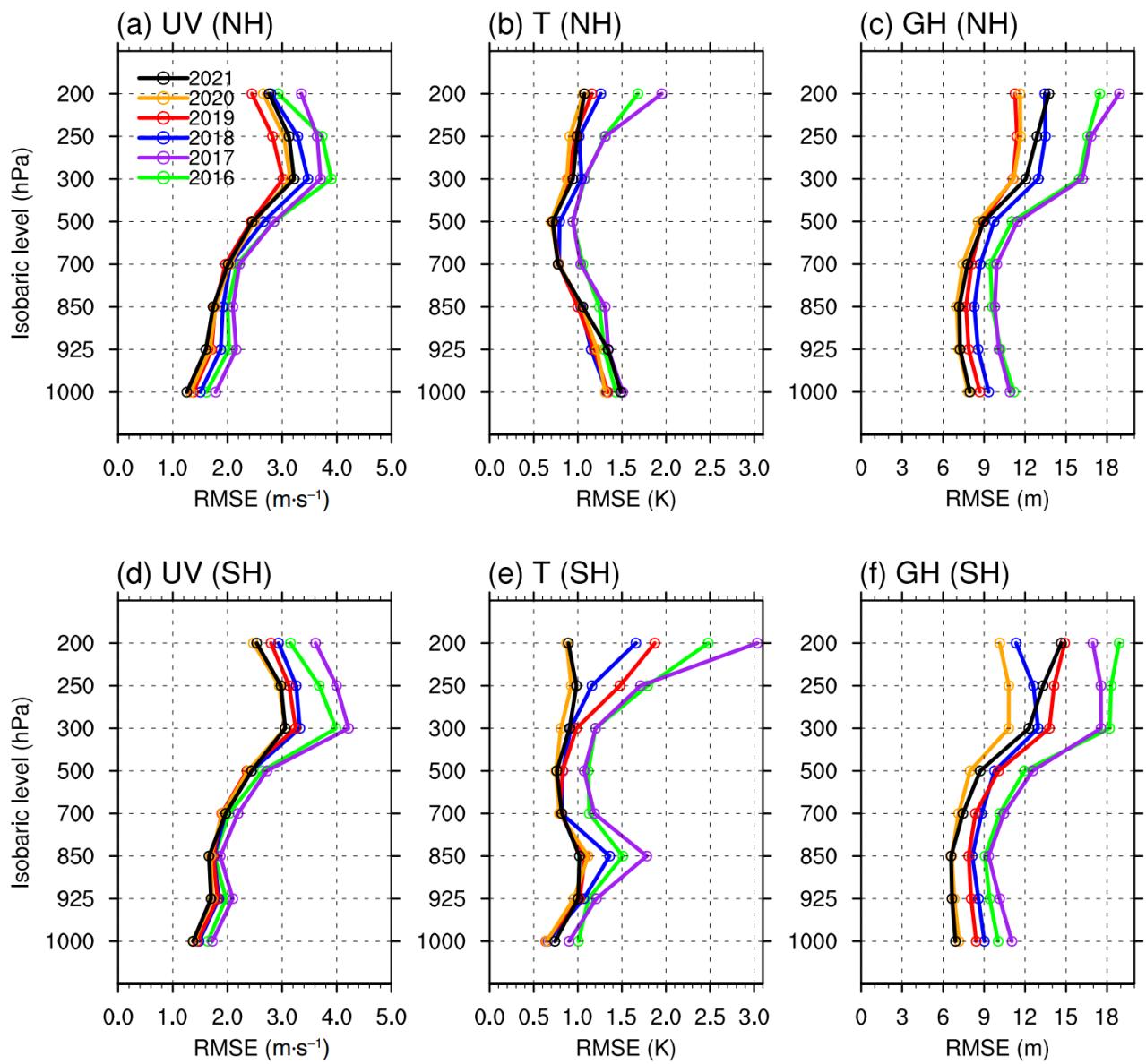
GRAPES_GFS real-time DA/Prediction system

NH: N30-70 degs; SH: S30-70 degs;

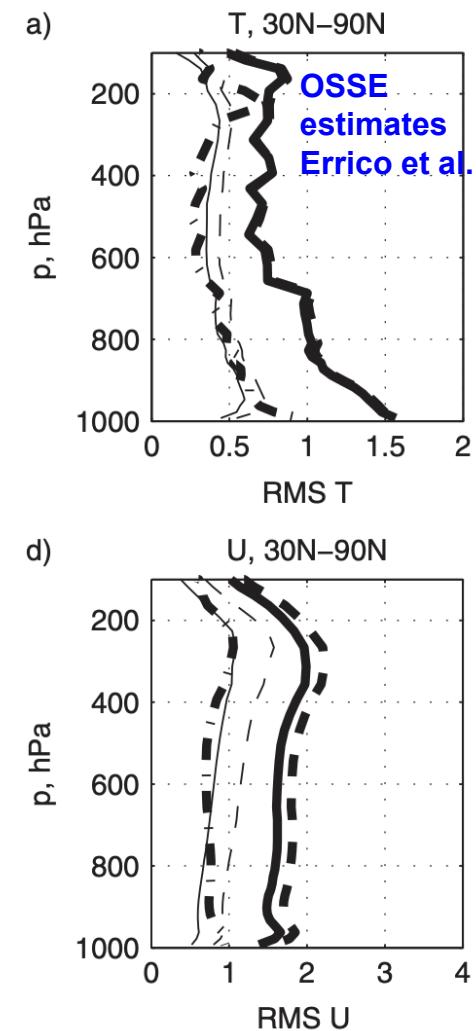


- Good fitting of perceived error variance
- Analysis error variance negligible at early lead times

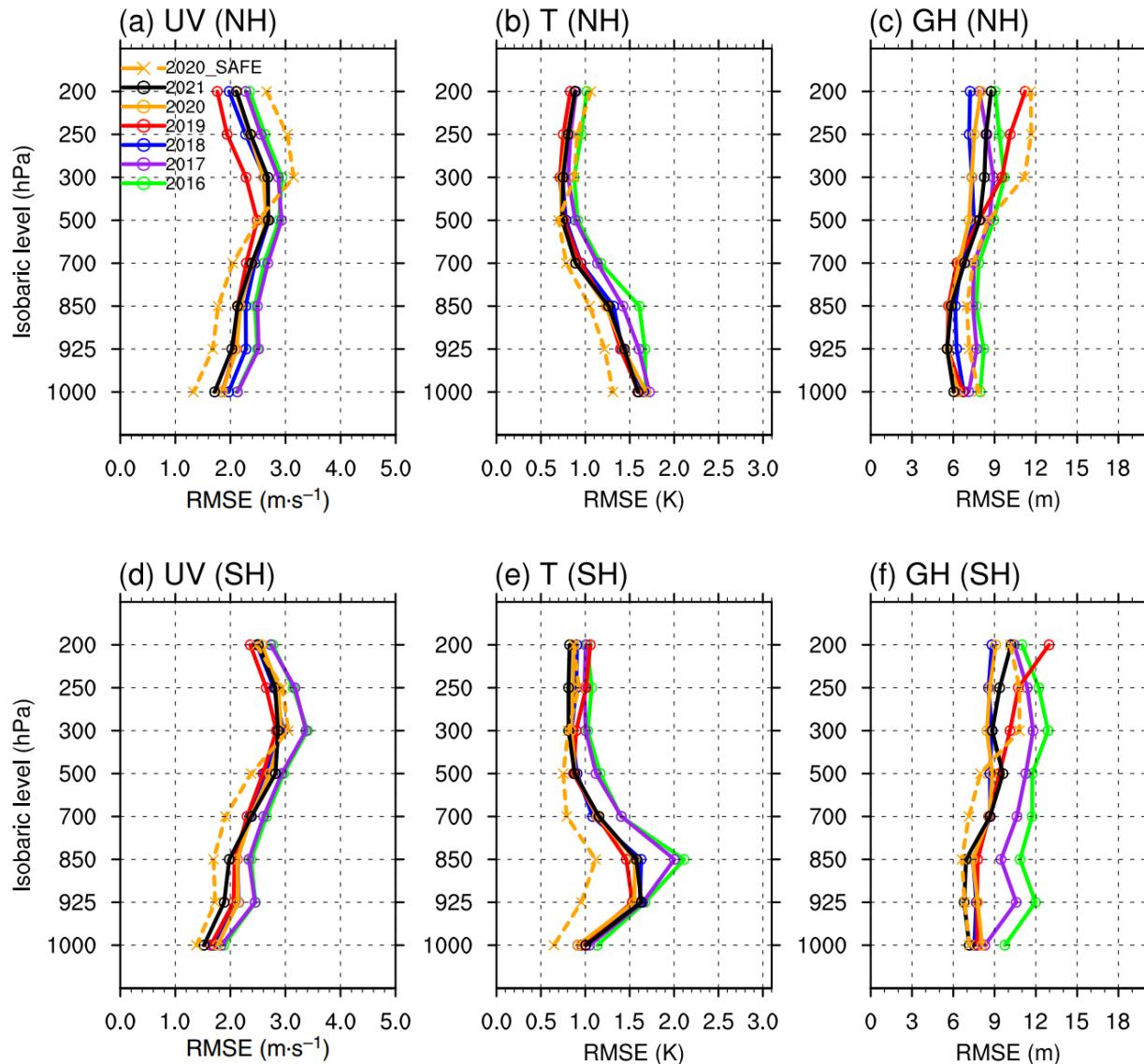
Annual Variation of Analysis Error - SAFE



- 分析误差廓线结构较为合理
- 2016, 17和之后分析误差明显减小

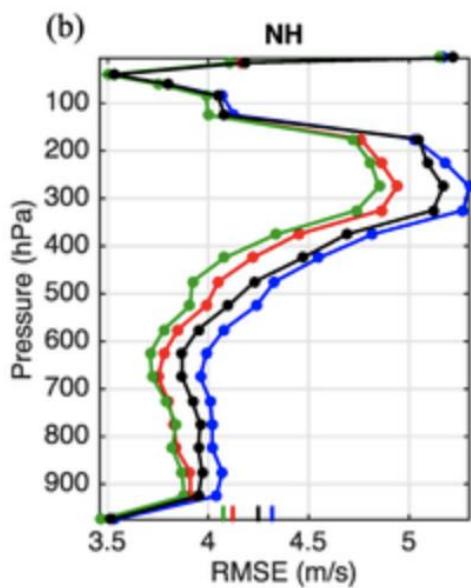


Annual Variation of Analysis Error - vs. ERA Reanalysis

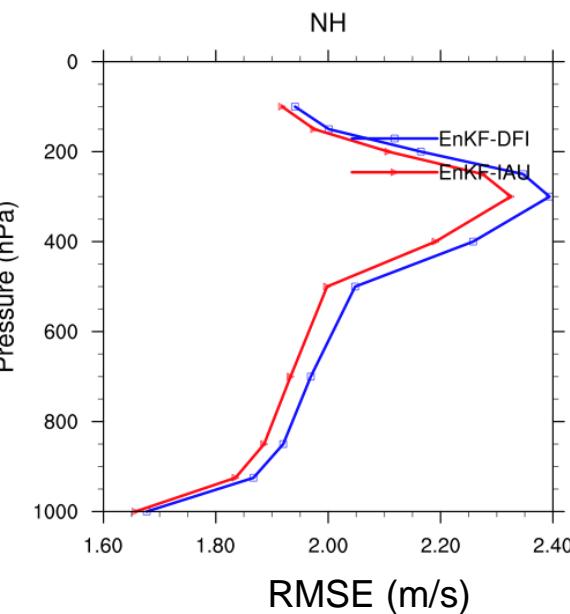


- ERA检验存在一定不合理
 - UV, GH的300和500hPa分析误差非常接近
- ERA检验相比SAFE
 - 500hPa以上低估
 - 500hPa以下高估

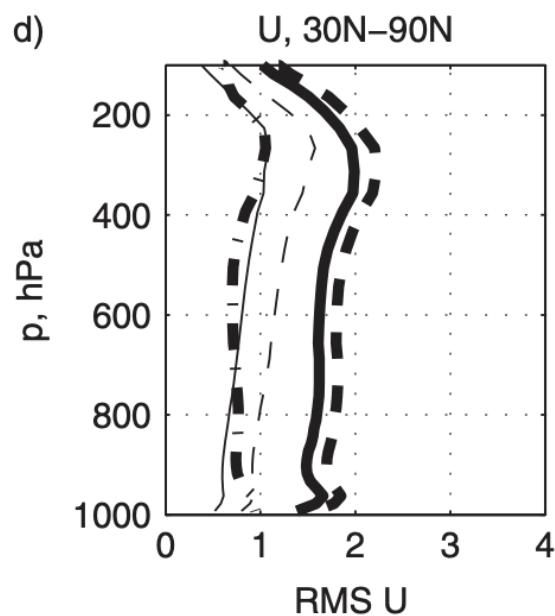
代表性误差?



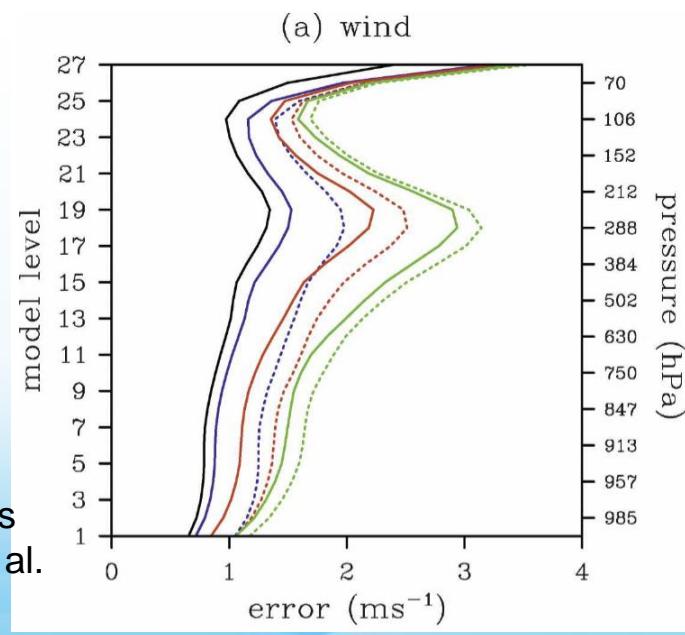
Lei et al. 2016



Lei et al.



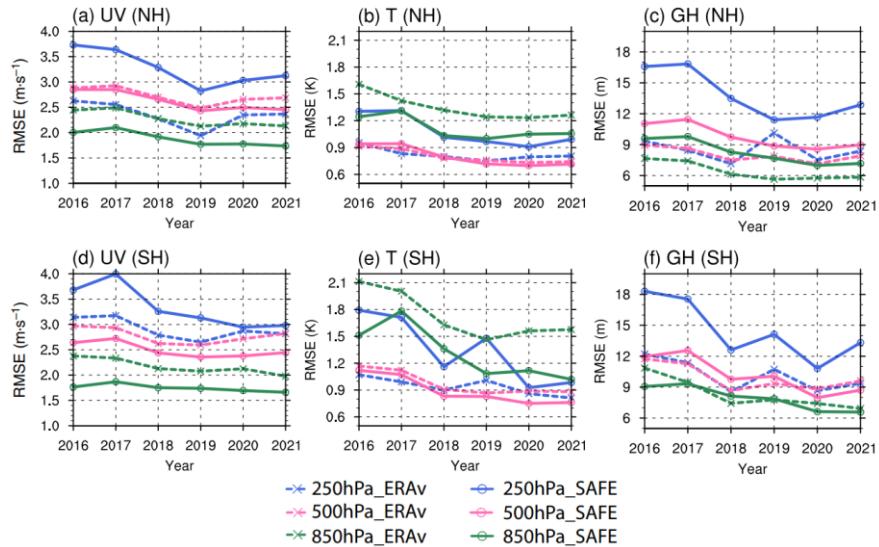
OSSE
estimates
Errico et al.



Wang et al. 2008

Annual Variation of Analysis Error - SAFE

分析误差随时间演变



- ERAv和SAFE反映的趋势相似，但存在系统性偏差

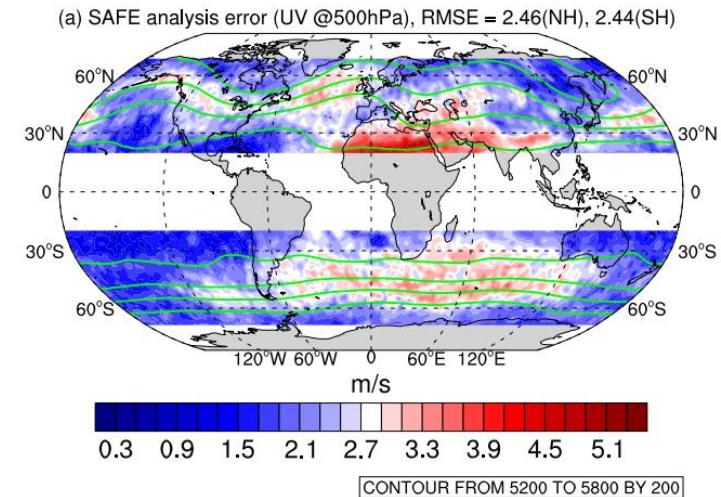
分析误差相对前一年的相对变化

		2017 [↓]	2018 [↓]	2019 [↓]	2020 [↓]	2021 [↓]
UV	250 hPa [↓]	-2% [↓]	-10% [↓]	-14% [↓]	7% [↓]	3% [↓]
		0% [↓]	-7% [↓]	-9% [↓]	3% [↓]	-2% [↓]
		5% [↓]	-9% [↓]	-8% [↓]	0% [↓]	-2% [↓]
	500 hPa [↓]	9% [↓]	-18% [↓]	-4% [↓]	-6% [↓]	1% [↓]
		3% [↓]	-10% [↓]	-3% [↓]	1% [↓]	3% [↓]
		6% [↓]	-6% [↓]	-1% [↓]	-2% [↓]	-2% [↓]
T	250 hPa [↓]	1% [↓]	-23% [↓]	-5% [↓]	-6% [↓]	9% [↓]
		0% [↓]	-16% [↓]	-10% [↓]	-3% [↓]	2% [↓]
		5% [↓]	-21% [↓]	-3% [↓]	5% [↓]	1% [↓]
	500 hPa [↓]	-5% [↓]	-32% [↓]	27% [↓]	-37% [↓]	6% [↓]
		-4% [↓]	-23% [↓]	0% [↓]	-9% [↓]	1% [↓]
		18% [↓]	-24% [↓]	-20% [↓]	3% [↓]	-9% [↓]
GH	250 hPa [↓]	1% [↓]	-20% [↓]	-15% [↓]	2% [↓]	10% [↓]
		4% [↓]	-15% [↓]	-9% [↓]	-3% [↓]	5% [↓]
		2% [↓]	-15% [↓]	-7% [↓]	-9% [↓]	3% [↓]
	500 hPa [↓]	-4% [↓]	-28% [↓]	12% [↓]	-23% [↓]	23% [↓]
		5% [↓]	-22% [↓]	3% [↓]	-21% [↓]	9% [↓]
		3% [↓]	-13% [↓]	-3% [↓]	-16% [↓]	-1% [↓]

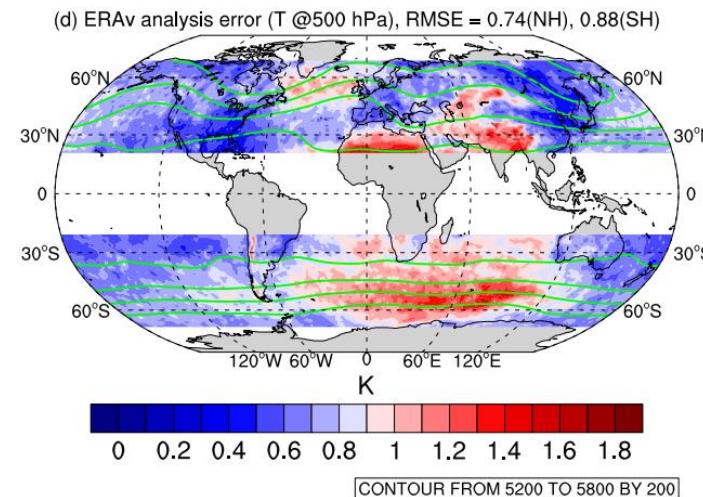
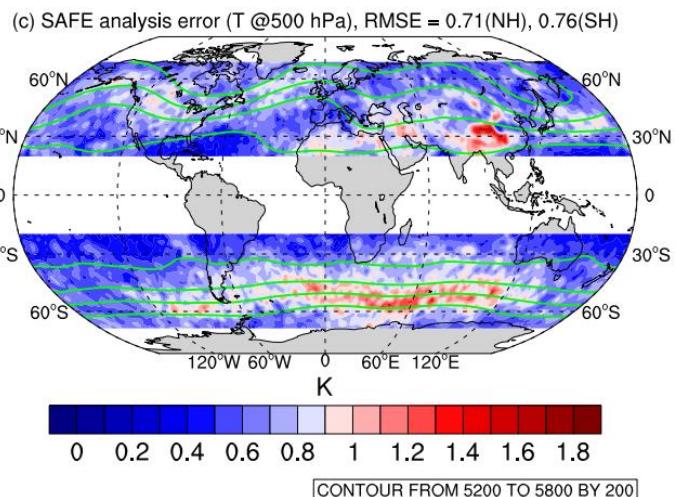
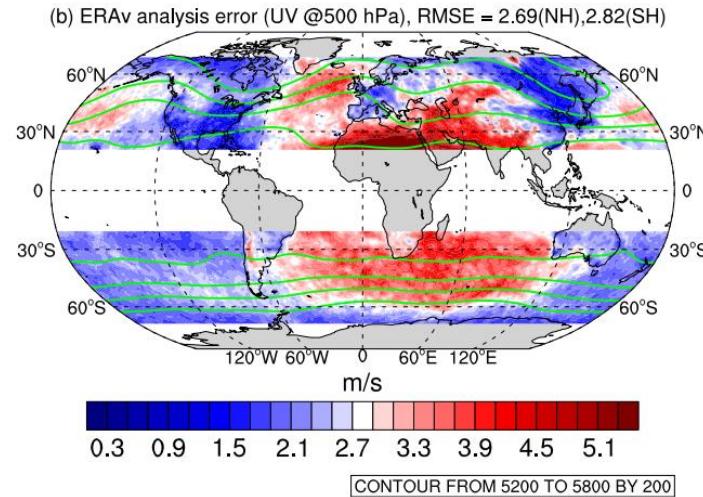
- 2017vs2016变化相对较小
 - 平均4%
- 2018vs2017显著减小
 - 平均17%，尤其在250hPa, ~22%
 - UV (10%), T(23%), GH(19%)
 - 3DVAR to 4DVAR
- 2019vs2018有一定减小
 - 尤其对NH~9%
 - 模式物理改进CU；更多卫星观测同化, e.g., FY-4A GIIRS
- 2020vs2019有一定减小
 - 尤其对T, GH in SH, ~18%
 - 更多卫星观测同化, e.g., FY-3D

Spatial Distribution of Analysis Error@500 hPa (2021)

SAFE



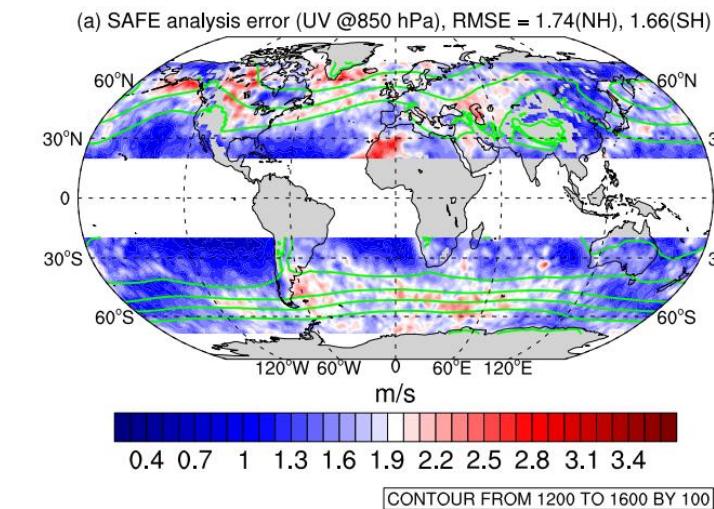
ERAv



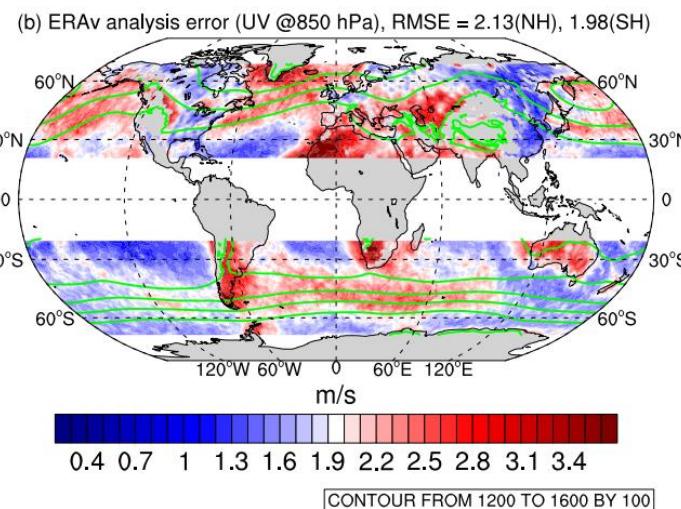
SAFE和ERAv分析误差空间结构类似，但后者整体高估

Spatial Distribution of Analysis Error@850 hPa (2021)

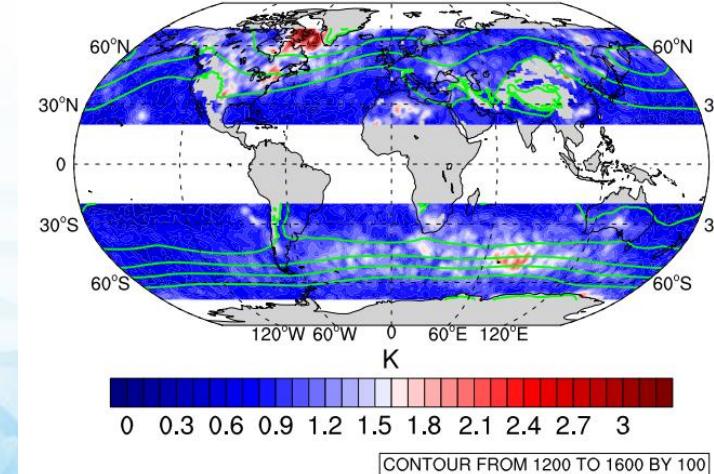
SAFE



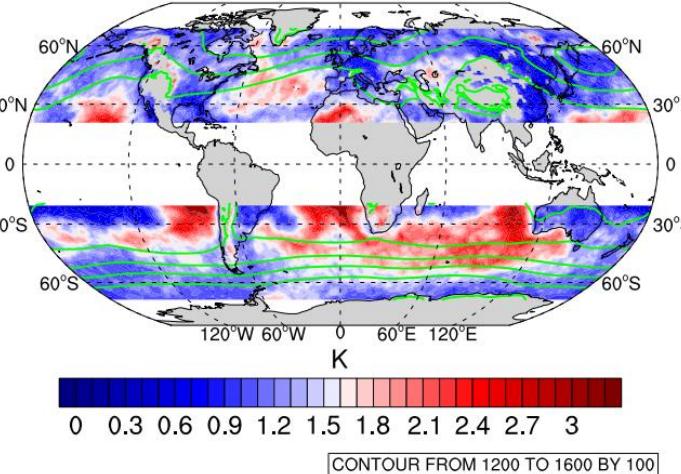
ERAv



(c) SAFE analysis error (T @850 hPa), RMSE = 1.06(NH), 1.02(SH)



(d) ERAv analysis error (T @850 hPa), RMSE = 1.26(NH), 1.58(SH)



SAFE和ERAv分析误差空间结构相似性比500hPa下降，
后者整体高估

Summary

- SAFE方法可以提供GRAPES系统同化分析场误差的可信估计
- GRAPES区域平均分析误差2016-2021改进明显
 - 2017-2018, UV (10%), T(23%), GH(19%)
同化方案3DVar升级至4DVar
 - 2018-2020, NH~9%, T, GH in SH, ~18%
模式物理改进，加入多种卫星观测同化
- GRAPES格点分析以及24-hr预报误差估计较合理
 - ERAv存在明显bias

Discussion

- 和其它中心分析场对比的检验方法存在问题
- 不同的误差估计方法
 - SAFE (1. 有理论基础；2. 假定合理无偏)
 - Other methods (1. 经验性估计, 2. 存在偏差)
- 资料同化、集合预报中的应用，大气海洋模式中的应用.....

Thanks for listening!

fengjiefj@fudan.edu.cn

- **Feng, J.***, Z. Toth, and M. Peña, **2017**: Spatial Extended Estimates of Analysis and Short-Range Forecast Error Variances. *Tellus A*, 69:1, 1325301.
- **Feng, J.***, Z. Toth, M. Pena, and J. Zhang, **2020**: Partition of Analysis and Forecast Error Variance into Growing and Decaying Components. *Quart. J. Roy. Meteor. Soc.*, 146(728), 1302-1321.
- **Feng, J**, et al. **2022**: Spatiotemporal estimation of analysis errors in the operational global data assimilation system at the China Meteorological Administration using a novel statistical method, *QJRMS*, DOI: 10.1002/qj.4507.
- Pena, M. and Toth, Z. 2014. Estimation of analysis and forecast error variances. *Tellus* 66A, 21767.